

METADATA FOR NASA GODDARD'S LIDAR, HYPERSPECTRAL AND THERMAL (G-LiHT) AIRBORNE IMAGER

CONTENTS

- 1) Contact information
- 2) Campaign description
- 3) Flight plans
- 4) Acquisition details
- 5) Field observations
- 6) Output file name(s)
- 7) Data products
- 8) Instrument specifications
- 9) Publications

1) CONTACT INFORMATION

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2) CAMPAIGN INFORMATION

Date(s): April - May 2013
Time of day: AM -Noon
Location: Mexico
Description: ICESat GLASS LiDAR under flights & FIA Forest Sampling
Research project: AMIGA-Carb
Funding source: NASA, Carbon Cycle Science

3) FLIGHT PLANS

Series of long ICESat satellite transects and transects covering a number of Mexican forest inventory plots.

4) ACQUISITION DETAILS

Aircraft: Piper Cherokee, N4118R
Pilot: Thaddeus Fickel, Infrared Barron LLC
G-LiHT operator(s): Hank Margolis NASA GSFC
Nominal altitude (AGL): 335 m AGL
Nominal velocity: 110-150 kt
Other:

5) FIELD OBSERVATIONS

Weather:
Other notes: VFR

6) OUTPUT FILE NAME(S)

AMIGACarb_AM_Guan_Chihuahua_GLAS_May2013
AMIGACarb_Chiap_Campeche_NFI_Apr2013
AMIGACarb_Chiaps_1_GLAS_Apr2013
AMIGACarb_Chiaps_1_NFI_Apr2013
AMIGACarb_Chihua_Sud_GLAS_May2013
AMIGACarb_Chihua_Sud_NFI_May2013
AMIGACarb_Chihuahua_norte_GLAS_May2013
AMIGACarb_Chihuahua_norte_NFI_May2013
AMIGACarb_Cuern_Oax_PM_NFI_Apr2013
AMIGACarb_G5_Oax_GLAS_Apr2013
AMIGACarb_Guan_Oax_1_NFI_Apr2013
AMIGACarb_Guan_Potosi_1_Apr2013
AMIGACarb_Guan_Potosi_1_GLAS_Apr2013
AMIGACarb_Guan_Potosi_1_NFI_Apr2013
AMIGACarb_Herm_AM_GLAS_Apr2013
AMIGACarb_Herm_AM_NFI_Apr2013
AMIGACarb_Herm_Guan_GLAS_Apr2013
AMIGACarb_Herm_Guan_NFI_Apr2013
AMIGACarb_HermMx_PM_GLAS_Jun2013
AMIGACarb_Oax_Chiap_1_GLAS_Apr2013
AMIGACarb_Oax_Chiap_1_NFI_Apr2013

AMIGACarb_Oax_local_1_GLAS_Apr2013
AMIGACarb_Oax_local_1_NFI_Apr2013
AMIGACarb_Out_of_the_Yuc_GLAS_May2013
AMIGACarb_Out_of_the_Yuc_NFI_May2013
AMIGACarb_PM_Guan_Chihuahua_GLAS_May2013
AMIGACarb_PM1_Herm_Guan_GLAS_Apr2013
AMIGACarb_PozaRica_Hidalgo_NFI_May2013
AMIGACarb_Yuc_Centro_GLAS_Apr2013
AMIGACarb_Yuc_Centro_NFI_Apr2013
AMIGACarb_Yuc_Norte_GLAS_Apr2013
AMIGACarb_Yuc_Norte_NFI_Apr2013
AMIGACarb_Yuc_North_2_GLAS_Apr2013
AMIGACarb_Yuc_North_2_NFI_Apr2013
AMIGACarb_Yuc_South_GLAS_Apr2013
AMIGACarb_Yuc_South_NFI_Apr2013
Hidalgo_May2013
Kuic1_Apr2013
Kuic2_Apr2013
Kuic3_Apr2013

7) DATA PRODUCTS

GPS-INS

Trajectory: Aircraft location and orientation (roll, pitch, yaw). Available as 3D Google Earth overlay (KML) and 250 Hz data product (ASCII).

LiDAR

Canopy Height Model: Lidar-derived maximum canopy height (m AGL) and canopy rugosity (i.e., standard deviation of heights within an area equivalent to a 1/24 ac USFS-FIA subplot). Available as Google Earth overlay (KML) and raster data product (GeoTIFF) at a nominal 1 m spatial resolution.

Digital Terrain Model: Lidar-derived bare earth elevation (m, EGM96 geoid), aspect and slope. Available as Google Earth overlay (KML) and raster data product (GeoTIFF) at a nominal 1 m spatial resolution.

Lidar Apparent Reflectance: Mean reflectance for all, single returns from a 1550 nm laser. The lidar is factory calibrated and data corrected for ranging distance, but not scan angle or atmospheric interactions. Available as raster data product (GeoTIFF) at a nominal 1 m spatial resolution.

Lidar Point Cloud: Individual lidar return data, including 3D coordinates; classified ground returns ("Classification" field); AGL heights ("Point Source ID Text" field, using z scale factor and offsets); and lidar apparent reflectance ("Intensity" field; -15 to -5 dB for 2 byte range). Overlapping swaths are co-aligned with coincident ground returns to remove swath-to-swath elevation biases. Available in ASPRS LAS 1.1 format.

Lidar Metrics: Common lidar height, density, fractional cover and return statistics (e.g., mean pulse density, returns per pulse) for all returns +/- 15 degrees of nadir. Available as raster data product (GeoTIFF) at a nominal 13 m spatial resolution (area equivalent to a 1/24 ac USFS-FIA subplot).

Image Spectrometer

All VNIR (418 to 918 nm, 4.5 nm sampling interval) data products are available as orthorectified raster files (ENVI file format) at a nominal 1 m spatial resolution; Google Earth overlays (KML) are available for the NIR band.

Radiance: Calibrated radiance data is provided for individual swaths in radiometric units ($W m^{-2} sr^{-1} nm^{-1}$).

At-sensor reflectance: Computed as the ratio between observed upwelling radiance and downwelling hemispheric irradiance; corrected for differences in cross-track illumination and BRDF using an empirically derived multiplier. At a nominal flying height of 335 m AGL, the at-sensor reflectance is a close approximation of surface reflectance. Available for individual swaths, and mosaicked for mapped areas using swath observations closest to nadir.

Vegetation indices: Computed from at-sensor reflectance data. These products are used as indicators of canopy properties and condition (e.g., greenness, pigment concentrations).

Ancillary data: Contains acquisition time, aircraft location, sun-sensor geometry, incoming PAR, clearness index, swath ID, and flag indicating nearest neighbor resampling during georegistration.

Thermal

Radiant temperature: Computed with 0.98 emissivity and no atmospheric or view angle correction. Available as Google Earth overlay (KML) and raster data product (GeoTIFF) at a nominal 1 m spatial resolution.

8) INSTRUMENT SPECIFICATIONS

GPS-INS

Model/Make: RT-4041, GPS and GLONAS enabled; Oxford Technical Solutions, Oxfordshire, UK
Serial number: 663
Sampling interval: 250 Hz
Differential correction: OmniStar HP or G2
Positional accuracy (1 sigma): 10 to 15 cm horizontal (vertical=horizontal*1.5)
Yaw accuracy (1 sigma): 0.1 degree
Roll accuracy (1 sigma): 0.03 degree
Pitch accuracy (1 sigma): 0.03 degree
Antenna: Antcom G5Ant-42AT1 L1/L2 Glonas/GPS/OmniStar
Post-Processing software: RT Post-Process

Scanning lidar

Model/Make: VQ-480; Riegl Laser Measurement Systems, Horn, Austria
Serial number: S9997785
Laser wavelength: 1550 nm
Pulse width: 3 ns
Pulse energy: 2817 nJ in 25 mm
Beam divergence: 0.3 mrad
Nominal footprint size: diameter = $\tan(\text{beam divergence}/2) * \text{altitude} * 2$
Laser pulse repetition frequency (PRF): 300 kHz
Effective measurement frequency: $0.5 * \text{PRF}$
Maximum number of returns per pulse: 8
Field of view: 60 degrees (+/- 30 degrees of nadir)
Scan mode: line
Scan rate: 100 lines per second
Nominal distance between points in a scan line: 0.24 m
Nominal distance between scan lines: 0.56 m
Swath size: width = $\tan(\text{FOV}/2) * \text{altitude} * 2$
Lever arm (ahead, left, above; date): 0.371, 0.142, 0.977 m (28 Aug 2012)
Boresight (roll, pitch, yaw; date): 0.02654, 0.01437, -0.40112 degrees (13 March 2013)
Post-Processing software: RiProcess

Profiling lidar: none

Digital SLR: none

Imaging spectrometer

Model/Make: Hyperspec model 1002A-00451; Headwall Photonics, Fitchburg, MA
Serial Number: G4-105
Camera: Adimec model RA1000m/D_DFG
Serial Number: 830016
Focal plane array: pushbroom, 1004 cross track pixels
Frame rate: 50 Hz
Lens/FOV: 8 mm lens, f/2; ~50 degree
Sensor size: 7.4 mm
Integration time: 20 msecs
Sensor range: 417-1008 nm
Spectral band width (FWHM): ~8 to 15 nm
Sampling resolution: 1.5 nm (401 bands)
Resampled resolution: 418 to 919 nm in 4.5 nm bands (114 bands)
Quantization: 12 bit

Thermal camera

Model/Make: Gobi-384; Xenics, Leuven, Belgium
Serial number: GOBI-1413
Sensor: Uncooled microbolometer

Focal plane array: 384 x 288 on 25 um pixels
Data output: degrees Celsius
Frame rate: 25 Hz
Sensitivity: 8 to 14 um
Quantization: 16 bit

Downwelling irradiance

Model/Make: USB-4000; Ocean Optics, Dunedin, FL
Serial number: USB4H02819
FOV: 180 degrees (cosine diffusor)
Integration time: 33 ms
Sample averaging: 30
Sampling interval: 0.6 nm
Sensor range: 380-1100 nm
FWHM: 1.5 nm
Resampled resolution: 418 to 919 nm in 4.5 nm bands (114 bands)
Quantization: 16 bit

9) PUBLICATIONS

Cook, B. D., L. W. Corp, R. F. Nelson, E. M. Middleton, D. C. Morton, J. T. McCorke1, J. G. Masek, K. J. Ranson, and V. Ly. 2013. NASA Goddard's Lidar, Hyperspectral and Thermal (G-LiHT) airborne imager. Remote Sensing 5:4045-4066, doi:10.3390/rs5084045.